

Scavenger: A Cloud Service for Optimizing Cost and Performance of ML Training Sahil Tyagi and Prateek Sharma {styagi, prateeks}@iu.edu

Problem

- Given wide array of size and types of VMs available in the cloud, challenging to find right cluster configuration in the cloud
- Incorrect allocation either increases training time or cost of ML training.
- Is there a way to find correct cluster configuration?

Contributions

- Scavenger finds ideal configuration reducing time by 2x!
- Online, black-box method that predicts time and cost of a training job with 98% accuracy
- Builds parallel and statistical performance models with minor overheads

Research Questions

- How effective is gradient noise as an indicator of statistical efficiency?
- How accurate is our performance and cost model across different job configurations?
- What are the performance and cost tradeoffs for different cost models in the cloud?

Methodology

• Data-parallel training for K workers and batch B:

 $\mathbf{x}_{t+1} = \mathbf{x}_t - \eta \frac{1}{K} \frac{1}{b} \sum_{k=1}^{k=K} \nabla f(\mathbf{x}_{k,t})$

- Training scales-up by increasing B; scales-out by increasing K
- Not all work equally important as measured by Gradient Noise:

 $\gamma(t) = \frac{\mathbb{E}[\frac{1}{K} \sum_{k=1}^{K} ||g_t^{(k)}||^2]}{\mathbb{E}[||\tilde{g}_t||^2]}$

 Time and cost predicted by knowing total iterations needed, per-step time and VM price:

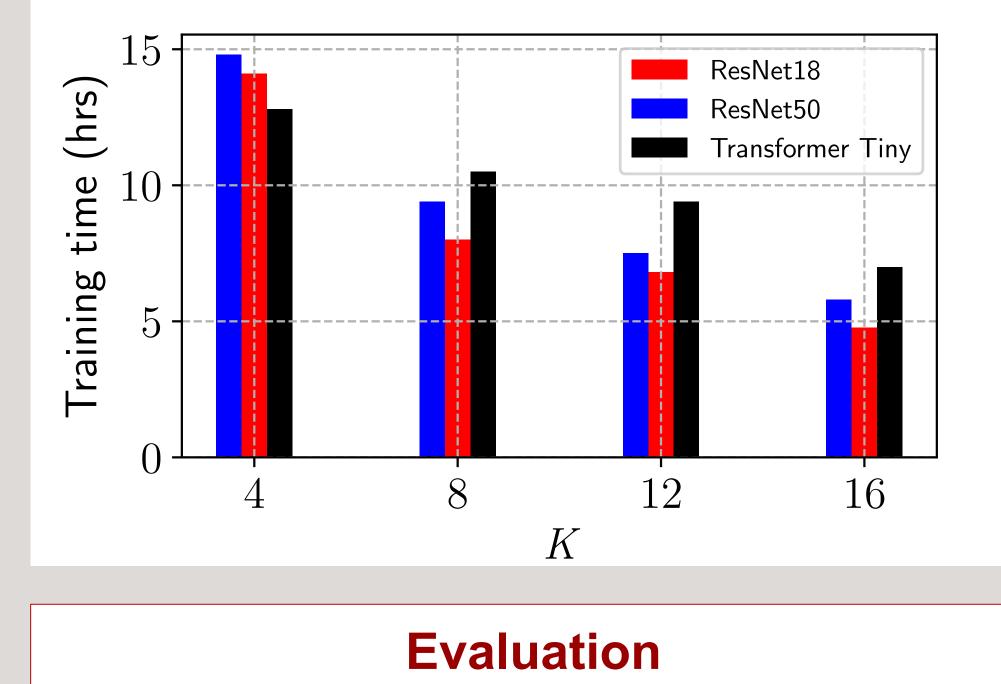
$$T = n_i \cdot \tau_1$$
 for $n_i = \frac{eD}{B}$ and $C = T \cdot K \cdot p$

• Statistical performance modeled by the relationship $e \propto \gamma \& \gamma \propto 1/\sqrt{B}$

 Build Gradient noise as scaling indictor for horizontal/vertical scaling

Horizontal scaling in the cloud

 Due to Amdahl's law, training does not scale linearly. Adding 4x resources does not reduce time by 4x!

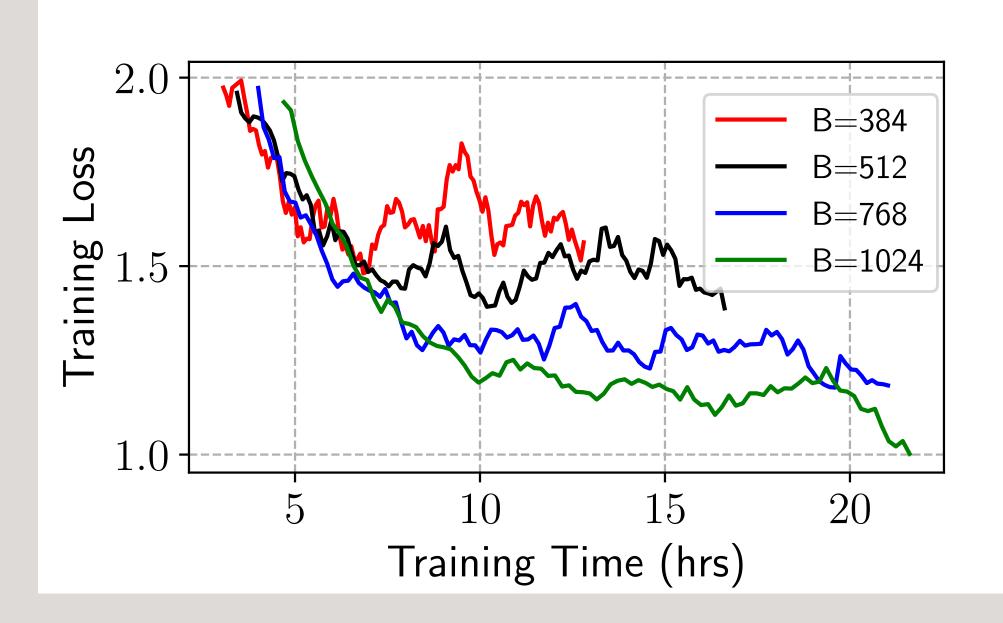


• What savings can be achieved with our job configurations & resource allocation policies?

Vertical scaling in the cloud

 Training with large batches is efficient and reduces time to training loss but increases memory utilization!

ResNet18



• Parallel performance models step time as:

 $t_{step} = t_{compute} + t_{sync}$ where $t_{compute} \propto b$ and $t_{sync} \propto K$

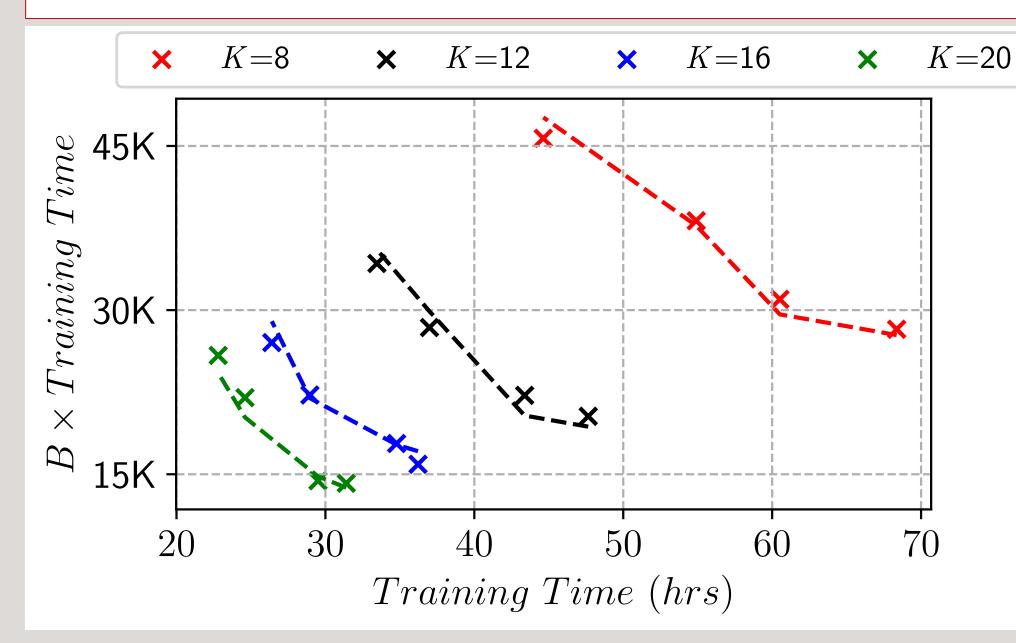
- Performance modeling uses either full-search, partial-search or no-search.
- Predict time and cost from model and build tradeoff curves; select configuration based on user preference: minimize time, minimize cost or knee-point

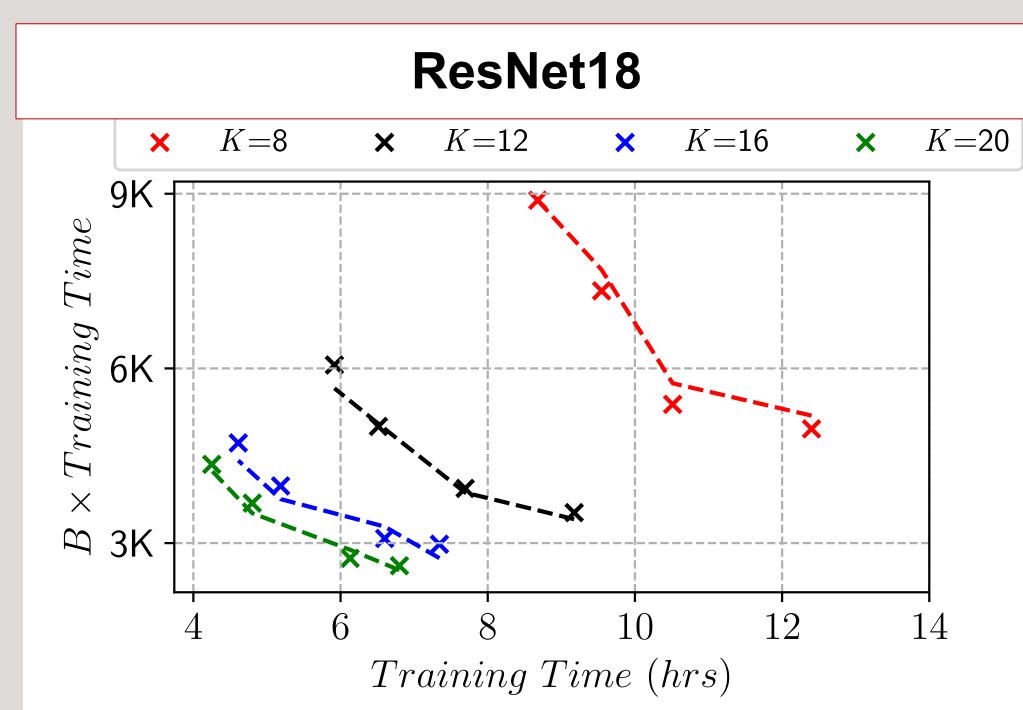
Prediction error of search techniques

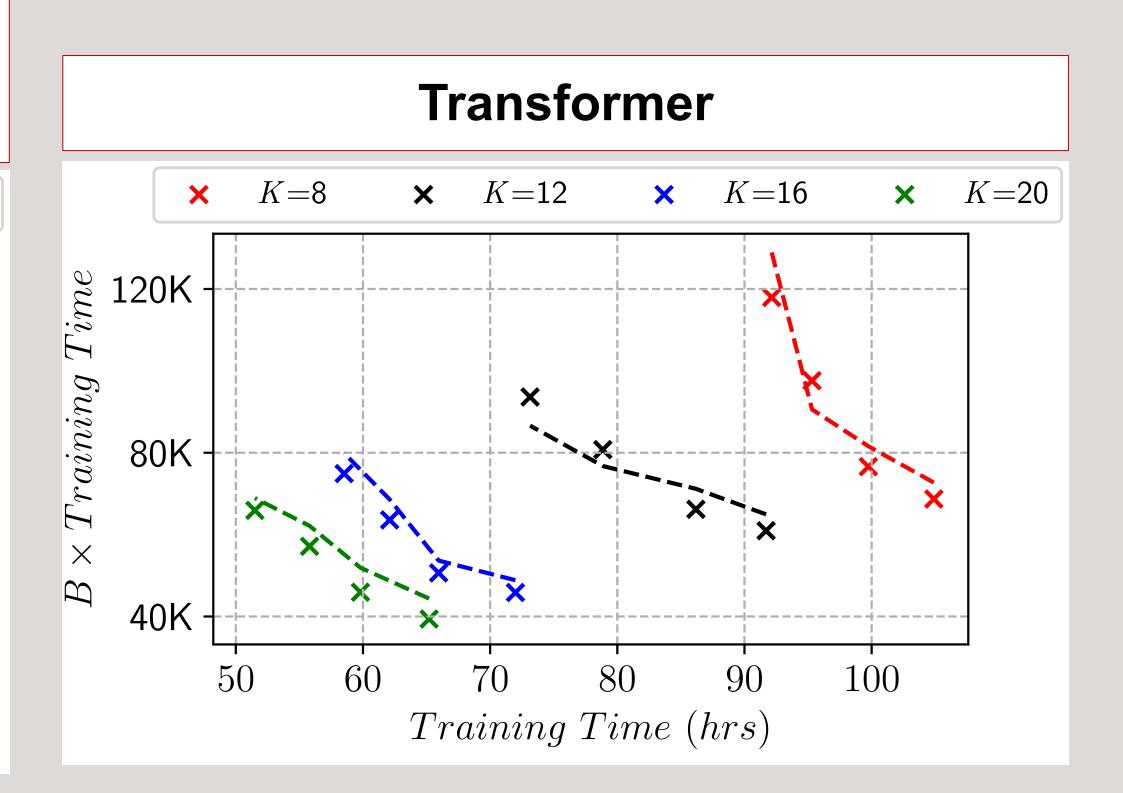
Full search runs each configuration so most accurate; partial search runs at extreme points and interpolates; universal model averages all prior models so least accurate.
Error between 4-20% only across all!

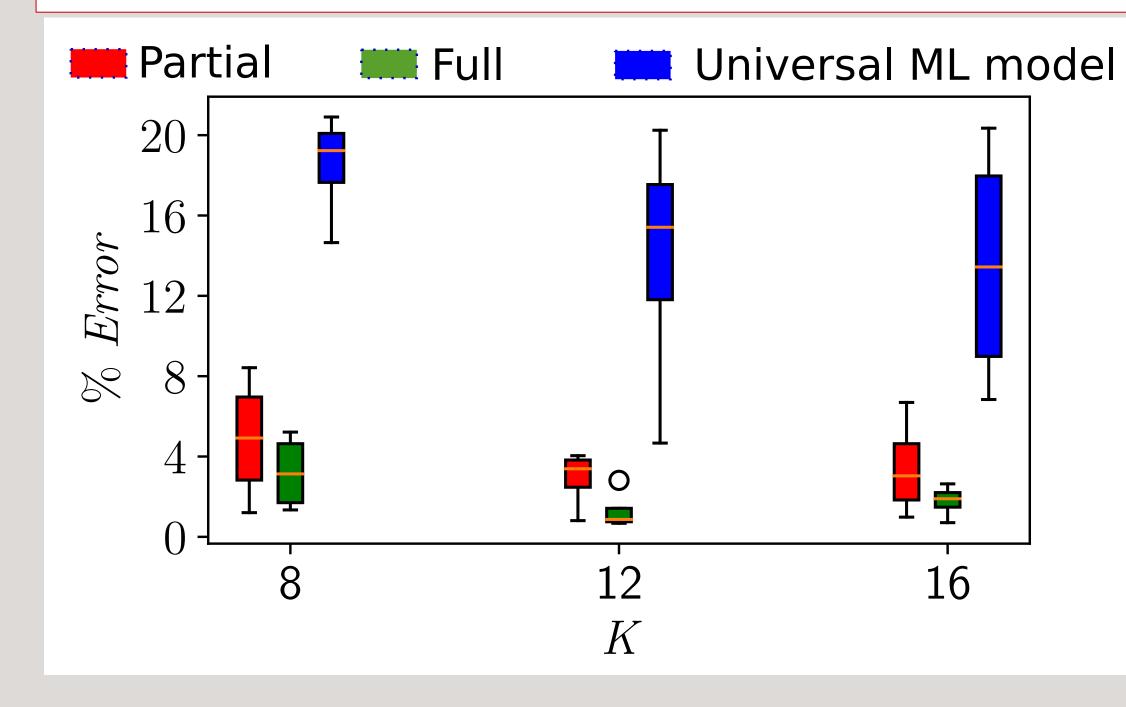
- Cost-Time tradeoff to converge for ResNet18, ResNet50 and Transformer
- VMs priced by memory allocated; For each K, models evaluated for B (384,512,768,1024)
- Scatter points are real time + cost of different (K,B) configurations
- Dashed line is performance predicted by Scavenger
- From the predicted and actual performance, tradeoff between time and cost exists and detected by Scavenger!

ResNet50









Conclusion:

 Scavenger uses online profiling and new parallel and statistical performance models for estimating the training performance on different cloud configurations, with high accuracy of over 98%, and reduces training time by 2×.

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